Shaft Couplings

Backlash-free Torque **Transmission** Compensation of Shaft Misalignment





IMG.900.V06.GB



mayr[®]-your reliable partner

What is your definition of reliability?

We define reliability as the highest product quality and competent service from the initial contact right up to the after-sale service

- Largest variety in selection of standard products
- Market leader's competence arising from decades of experience in the development, production and application of power transmission products
- Optimum product selection due to our expertise in design and calculation
- □ Reliable component dimensioning
- □ Intelligent platform (modular construction)
- □ High flexibility for individual requests and customer-tailored solutions
- Quality-inspected suppliers
- D Modern, highly robust materials
- □ 100% quality control
- □ Certified according to DIN EN ISO 9001:2000
- D Personal supervision from the first contact right up to the after-sale service
- □ Worldwide local service network
- CAD-files available online to save time and costs during construction
- □ 24-hour delivery service for preferred products
- □ Short delivery times and on-time delivery
- D Unlimited replacement part availability worldwide





A Worldwide Presence

Our Sales and Service network is constantly expanding. We guarantee you and your customers almost all over the world local representation. With eight branch firms in France, Switzerland, Italy, England, Poland, the USA, Singapore and China as well as around 30 representatives and eight subsidiaries in Germany, we provide local service for our customers in all important industrial areas.

Total Quality Management

Product Quality

Every delivery which leaves our firm has been subjected to a careful quality inspection, meaning that you are able to rely 100 % on $mayr^{\circledast}$ products. If required, we pre-adjust our clutches and brakes accurately to the requested values and confirm the product characteristics with an Inspection Report.

Quality Management

mayr[®] uses the term quality to describe its products and services. Certification of our quality management confirms the quality-consciousness of our colleagues at every level of the company.

Our integrated management system is certified according to DIN EN ISO 9001:2000 (Quality) and DIN EN ISO 14001 (Environment) and complies with the OHSAS 18001/OHRIS (Occupational Health and Safety) demands.





Individual and Flexible Logistics

Flexible and optimally qualified colleagues ensure that your order is delivered according to schedule and with the most appropriate delivery method. We take into account your individual packaging and dispatch regulations as a matter of course. Our modern high rack warehouse has a permanently available stock of our wide standard product selection.

And if you are really in a hurry, simply use our uniquely-quick basic product delivery service!





Construction and Development

Innovations for Your Success

With our innovative and economical solutions, we are able to set new records in the field of power transmission. Our many worldwide patents prove our constant ambition of developing better and technologically superior products.

Highly qualified engineers, high-performance 3D-CADsystems and the most up-to-date FEM calculation aids used in our Development and Construction departments mean that our business is perfectly equipped to offer our customers effective solutions.

Experts for all Power Transmission Questions

Exploit our know-how, gained by decades of experience in the development, production and application of drive technology products. Our experts in Construction and Development are happy to advise you personally and competently when selecting and dimensioning the drive solution you require.

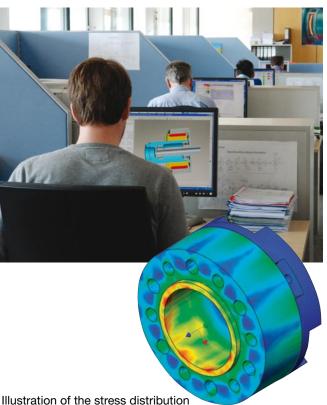


Illustration of the stress distribution in a backlash-free shaft connection

From Prototype to Finished Product

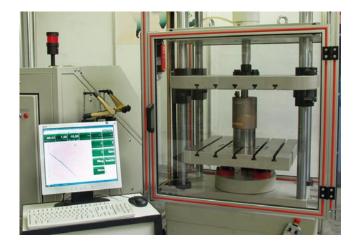
No mayr[®] product is released onto the market until it has proved its functional capabilities and reliability in extreme, long-term tests.

The spectrum of testing equipment is as varied as our range of products:

- Friction work test stands
- Wear test stands
- Noise measurement room with highly accurate noise measurement inspection devices
- □ Torque measurement stands up to 200.000 Nm
- □ Impact and alternating load test stands
- Force test stands
- Linear movement test stands
- Continuous performance test stands
- Magnetic flow measurement test stands
- □ High-speed test stands up to 20.000 rpm
- Misalignment and angular misalignment test stands
- Load and measurement test stands for DC motors

Product Data: Our 24-hour Service

Our website offers you detailed information 24 hours per day, 365 days per year with no delays. Here you can find not only the latest catalogues and technical documentation but also CAD-files for cost-saving construction of our products.



Unsurpassed -Our Standard Programme

For safety clutches, safety brakes, backlash-free shaft couplings and high-quality DC drives, we offer you a complete product range with market and branch optimised constructions and designs.



The Optimum Shaft Coupling for every Drive

Each drive has its own specific characteristics and therefore places different demands on the couplings which transmit the torque from one shaft to the second and which compensate for the resulting shaft misalignments. In most cases only backlash-free couplings are able to meet the requirements for high-speed, dynamic or reversing precision drives. *mayr*[®] power transmission has three of the most established and most attractive backlash-free shaft couplings in its programme:

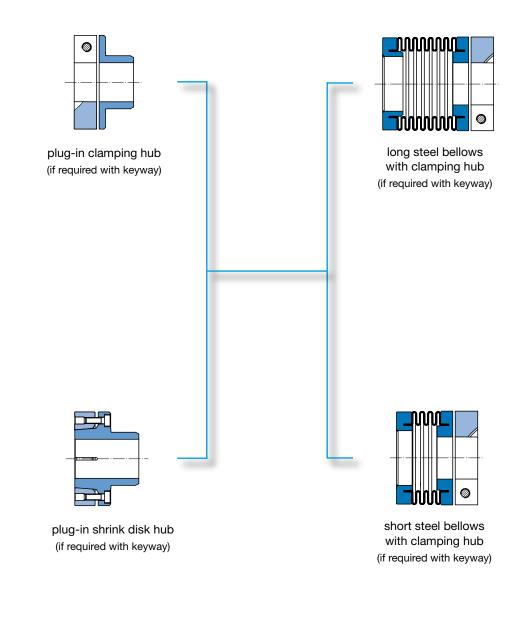
- Disk pack couplings,
- Steel bellows couplings and
- Elastomer couplings

Therefore, $mayr^{\otimes}$ offers an optimum solution for many different drives.

Overview: Backlash-free Shaft Couplings Types, Designs, Characteristics

| Image: Normal torque range in NmImage: Normal torque range in NmImage: Normal torque range in NmImage: Normal torque range in Nm24 - 120 $35 - 150$ $16 - 700$ $4 - 1040$ $190 - 24000$ $190 - 1600$ $22000 - 110$ Max. permitted speed in rpm 3600 22500 10000 28000 13600 9500 3600 Shaft diameter in mm $10 - 45$ $8 - 85$ $6 - 80$ $14 - 170$ $14 - 110$ on reque $10 - 45$ $10 - 45$ $8 - 85$ $6 - 80$ $14 - 170$ $14 - 110$ on reque $10 - 45$ $10 - 120$ 100 250 70 250 Torsionally rigid x Vibration damping x Can be combined with safety clutch x Can be integrated with torque measurement x x x x x Distance between shaft ends x x x x x | primeflex Steel bellows couplings | ROBA [®] -DS Servo couplings | smartflex [®] Steel bellows couplings | ROBA [®] -ES Elastomer couplings | ROBA [®] -DS All-steel couplings | EAS [®] -control-DS Torque measure- ment couplings | ROBA [®] -DS All-steel couplings |
|---|--|---|--|---|---|---|---|
| Image: Normal log of the state is a state in the state in the state is a state in the state in the state is a state in the state | Page 6 | Page 8 | Page 10 | Page 12 | Page 14 | Page 16 | Page 18 |
| Steel bellows Disk pack Steel bellows Plastic element Disk pack Disk pack </td <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> | | | | | | | |
| Nominal torque range in Nm 24 - 120 35 - 150 16 - 700 4 - 1040 190 - 24000 190 - 1600 22000 - 110 Max. permitted speed in rpm 3600 22500 10000 28000 13600 9500 3600 Staft diameter in mm 3600 22500 10000 28000 13600 9500 3600 Max. permitted speed in rpm 8 - 85 6 - 80 14 - 170 14 - 110 on reque Max. permanent operation temp. in °C 120 100 250 70 250 Torsionally rigid x x x x x x x X x x x x x x x x Max. permanent operation temp. in °C x x x x x x x x Yorsionally rigid x x x x x x x x Can be combined with safety clutch x x x x x x | | | | | | | |
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| | | | | | ^ | ^ | ^ |
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| Shaft misalignment compensation radial | | | | | ~ | ^ | ~ |
| | J. J | • | | | х | х | х |
| Shaft misalignment compensation angular | | | | | | | |
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| X X X | - | | | Х | x | | |
| Product catalogue P.933.VGB K.950.VGB K.932.VGB K.940.VGB K.950.VGB P.950000.V_ | | | K.932.V .GB | K.940.V .GB | K.950.V .GB | K.950.V .GB | P.950000.VGB |







According to German notation, decimal points in this catalogue are represented with a comma (e.g. 0,5 instead of 0.5). We reserve the right to make dimensional and constructional alterations.

For detailed information, detailed technical data and dimensions, please see our product catalogue P.933.V_ _.GB.

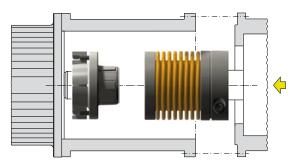


- Plug-in connection
- Backlash-free
- Can be de-installed even after longer operating periods without damaging the steel bellows
- Extremely compact and very high performance density
- Easy to install via clamping or shrink disk connections
- Frictionally-locking and positive-locking shaft-hub connections
- Excellent misalignment capability
- Can be variably dimensioned via the modular system
- Cost-effective





Installation Example

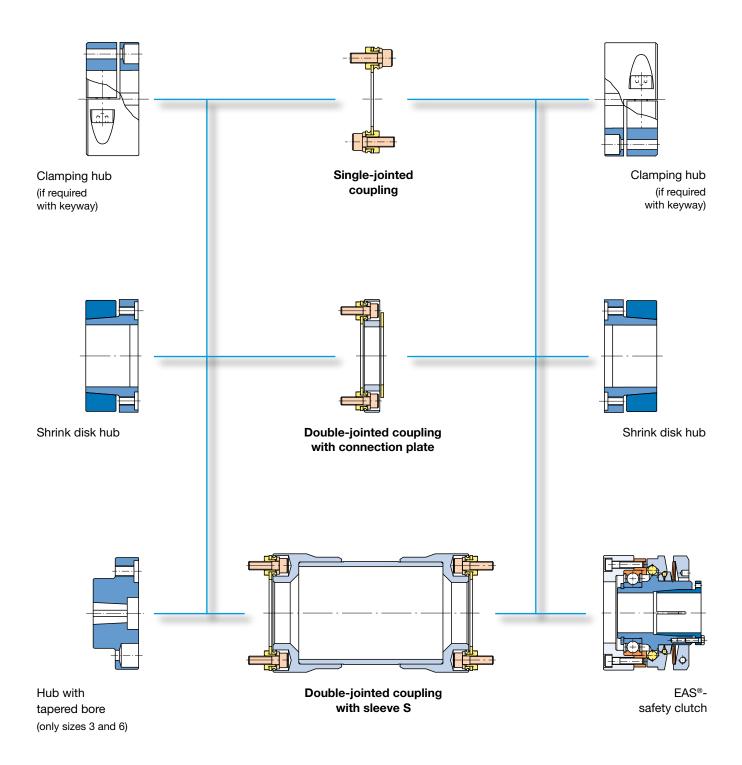


The primeflex[®]-steel bellows coupling transmits the torque backlash-free between the motor shaft and the gear shaft. By applying plug-in shrink disk hubs (see Installation Example) or plug-in clamping hubs, the primeflex[®]-steel bellows couplings can be mounted in areas which are difficult to access.

| Taa | hnical Data | Dimensions | | | | Size | |
|--|----------------|---------------------|------------------|--------------------------|------|------|------|
| Tec | ninical Data, | Dimensions | | | 1 | 2 | 3 |
| Nom | Nominal torque | | T _{KN} | [Nm] | 24 | 60 | 120 |
| Oute | Outer diameter | | | [mm] | 47 | 60 | 79 |
| ą | Minimum bor | e | | [mm] | 12 | 19 | 25 |
| Clamping hub | Maximum bo | re | | [mm] | 25 | 35 | 45 |
| pinç | Maximum spe | eed | n _{max} | [rpm] | 8000 | 6000 | 4000 |
| am | Longth | long steel bellows | | [mm] | 77 | 93 | 117 |
| Ö | Length | short steel bellows | | [mm] | 62 | 74 | 92 |
| | Axial | long steel bellows | ΔK_a | [mm] | 0,2 | 0,25 | 0,25 |
| a ' | displacement | short steel bellows | ΔK_a | [mm] | 0,1 | 0,15 | 0,15 |
| Permitted ¹⁾ iisalignment | Radial | long steel bellows | ΔK_r | [mm] | 0,2 | 0,3 | 0,3 |
| i mi aligi | misalignment | short steel bellows | ΔK_r | [mm] | 0,1 | 0,1 | 0,1 |
| Permitted ¹⁾ misalignments | Angular | long steel bellows | ΔK_{w} | [°] | 1 | 1 | 1 |
| - | misalignment | short steel bellows | ΔK_w | [°] | 1 | 1 | 1 |
| Torsi | onal | long steel bellows | C _T | [10 ³ Nm/rad] | 9 | 22 | 50 |
| sprin | g rigidity | short steel bellows | C _T | [10 ³ Nm/rad] | 18 | 44 | 100 |

1) The permitted misalignments must not simultaneously reach their max. value.







For detailed information, detailed technical data and dimensions, please see our product catalogue K.950.V_ _.GB.

This catalogue is also available for download as a pdf file on our website www.mayr.com.

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mayr®

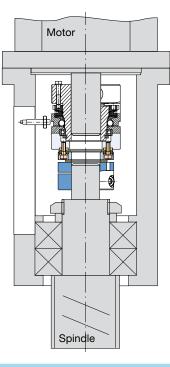
Characteristics and Advantages

- ROBA®-DS servo couplings are made of steel and highstrength aluminium alloys – the basis of these extremely compact designs.
- Due to their high performance density, they transmit high torques at comparably low volumes.
- Their low mass moment of inertia also predestines ROBA®-DS servo couplings for highly dynamic drive systems with high speeds.
- The flexible disk pack compensates for shaft misalignments and transmits the torque backlash-free with a high torsional rigidity.
- ROBA®-DS servo couplings are absolutely wear-free and maintenance-free.



Installation Example





ROBA®-DS shaft coupling combined with an EAS®safety clutch. Backlash-free and torsionally rigid torque transmission between the motor shaft and the spindle shaft. Compensation of axial, radial and angular misalignments.

| Technical Data, Dimensions | | | | | Size | | | | | | | |
|--|---|-----------------------|-------------------|---------------------------|------------------|------------------|------|------|--|--|--|--|
| Tec | fillical Data, D | | | | 3 | 6 | 10 | 15 | | | | |
| Nominal torque ¹⁾ | | T _{KN} | [Nm] | 35 | 60 | 100 | 150 | | | | | |
| Peak torque ²⁾ | | Τ _{κs} | [Nm] | 52 | 90 | 150 | 225 | | | | | |
| Alter | nating torque | | Τ _{κw} | [Nm] | 21 | 36 | 60 | 90 | | | | |
| Oute | er diameter | | | [mm] | 45 | 56 | 69 | 79 | | | | |
| qnq | Minimum bore | | | [mm] | 10 | 14 | 19 | 25 | | | | |
| g ht | Maximum bore | | | [mm] | 20 | 28 | 35 | 42 | | | | |
| Clamping | Maximum speed ³⁾ | | n _{max} | [rpm] | 13500 | 10800 | 9000 | 7800 | | | | |
| am | E Length single-jointed coupling | | | [mm] | 48,5 | 52,6 | 67 | 69,9 | | | | |
| Ö | Min. length dou | ble-jointed coupling | | [mm] | 59 | 64,7 | 79,5 | 82,8 | | | | |
| ∣ ⁴) ents | Axial displaceme | nt ^{5) 6)} | ΔK_a | [mm] | 0,5 | 0,7 | 0,9 | 1,1 | | | | |
| Permitted ⁴⁾ misalignments | Radial | with connection plate | ΔK_r | [mm] | 0,15 | 0,15 | 0,2 | 0,2 | | | | |
| ermi alig | ⁵ misalignment ⁵ with special sleeve ΔK_{rH} | | [mm] | | Please contact t | he manufacturer. | | | | | | |
| P. | $\Delta \overset{s}{=}$ Angular misalignment per disk pack ΔK_{w} [°] | | | 1,0 | 1,0 | 1,0 | 1,0 | | | | | |
| Torsi | onal spring rigidit | y disk pack | C _{T LP} | [10 ³ Nm/rad] | 17 | 35 | 60 | 145 | | | | |

1) Valid for max. permitted shaft misalignments.

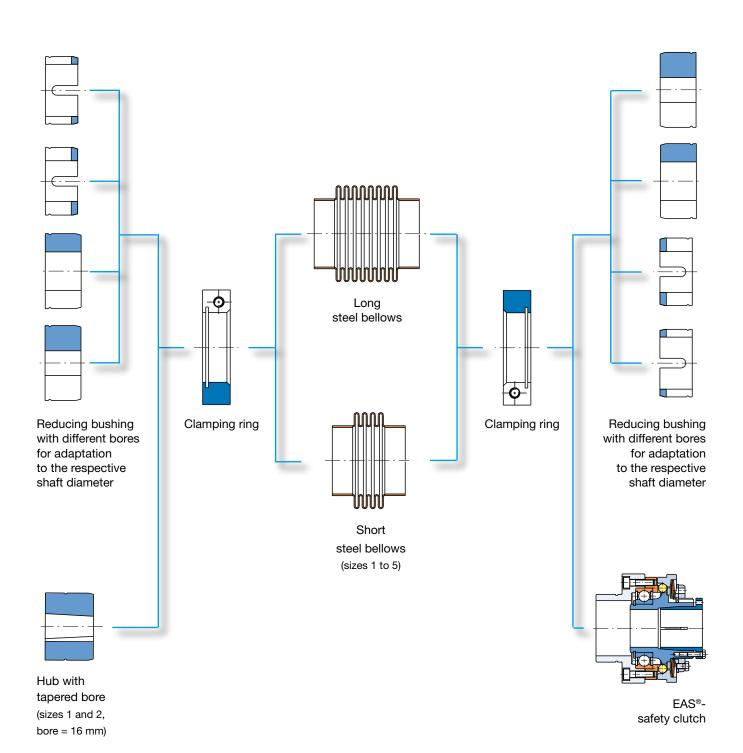
2) Valid for constant load direction, max. load cycles $\leq 10^5$.

3) Not valid for coupling with special sleeve.

4) The permitted misalignments must not simultaneously reach their max. value.5) The values refer to couplings with 2 disk packs.

6) Only permitted as a static or virtually static value.





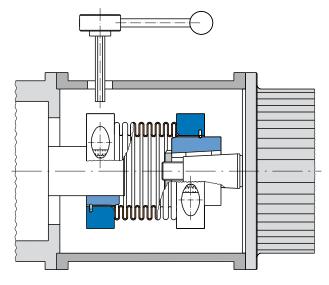
For detailed information, detailed technical data and dimensions, please see our product catalogue K.932.V_ _.GB.

- smartflex[®]-steel bellows couplings compensate for axial, angular and radial shaft misalignments.
- Backlash-free shaft attachment, backlash-free torque transmission and high torsional rigidity provide high precision in the drive line.
- The easy and fast shaft attachment saves installation time.
- Due to the ingeniously simple set-up, the priceperformance ratio is extremely advantageous.
- On radial misalignment, the misalignment capability of smartflex[®]-couplings is up to three times higher than the misalignment capability of common steel bellows couplings.
- The high misalignment capability eliminates the most common accident cause on previous generations of steel bellows.
- A flexible modular structure minimises storage and provides high availability.



Installation Example





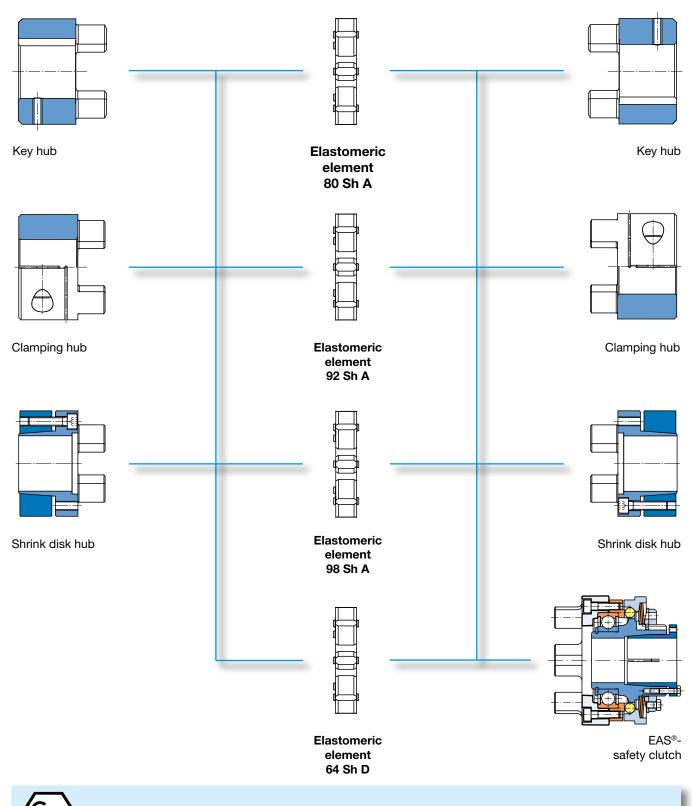
By applying clamping ring hubs, the smartflex[®]-steel bellows couplings can be mounted in areas which are difficult to access. Please provide an opening in the bell housing for the Allen wrench as depicted in the example.

| Taa | hnical Data | imonoiono | | | Size | | | | | | | | |
|--|---|---------------------|------------------|--------------------------|-------|------|------|------|------|------|--|--|--|
| Tec | hnical Data, D | amensions | | | 0 | 1 | 2 | 3 | 4 | 5 | | | |
| Nom | inal torque | | T _{KN} | [Nm] | 16 | 40 | 100 | 200 | 400 | 700 | | | |
| Oute | r diameter | | | [mm] | 46 | 57 | 72 | 94 | 118 | 146 | | | |
| | Minimum bore | | | [mm] | 8 | 11 | 16 | 18 | 30 | 40 | | | |
| ing 1g | Maximum bore | | | [mm] | 19 | 25 | 36 | 50 | 62 | 85 | | | |
| duc | Maximum bore Maximum speed long steel bellows | | n _{max} | [rpm] | 10000 | 8000 | 6000 | 4000 | 3000 | 2500 | | | |
| Bu bu | long steel bellows | | [mm] | 49,5 | 59,3 | 72 | 90,3 | 115 | 124 | | | | |
| | Length | short steel bellows | | [mm] | - | 43,7 | 52,5 | 65,6 | 87 | 98 | | | |
| | Axial | long steel bellows | ΔK_a | [mm] | 0,4 | 0,6 | 0,8 | 0,8 | 0,8 | 0,6 | | | |
| l ¹) ents | displacement | short steel bellows | ΔK_a | [mm] | - | 0,3 | 0,4 | 0,4 | 0,6 | 0,6 | | | |
| Permitted ¹⁾ misalignments | Radial | long steel bellows | ΔK_r | [mm] | 0,3 | 0,4 | 0,5 | 0,5 | 0,5 | 0,5 | | | |
| rmi | misalignment | short steel bellows | ΔK_r | [mm] | - | 0,1 | 0,1 | 0,1 | 0,1 | 0,1 | | | |
| Pe | Angular | long steel bellows | ΔK_w | [°] | 3 | 3 | 3 | 3 | 1,5 | 1,0 | | | |
| misalignment | misalignment | short steel bellows | ΔK_w | [°] | - | 1,5 | 1,5 | 1,5 | 1,2 | 1,0 | | | |
| Torsi | ional spring | long steel bellows | C _T | [10 ³ Nm/rad] | 4 | 9 | 22 | 50 | 125 | 305 | | | |
| · · · · · · · · · · · · · · · · · · · | | short steel bellows | C _T | [10 ³ Nm/rad] | - | 18 | 44 | 100 | 168 | 380 | | | |

1) The permitted misalignments must not simultaneously reach their max. value.







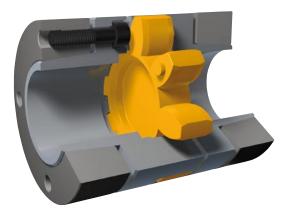
Also available in ATEX design according to the directive 94/9 EC (ATEX 95).

For detailed information, detailed technical data and dimensions, please see our product catalogue K.940.V_ _.GB.

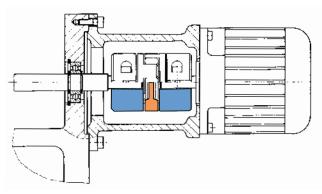
- ROBA[®]-ES couplings transmit the torque backlash-free via pre-tensioned elastomer elements and compensate for shaft misalignments.
- Rigidity and damping behaviour are variable due to four elastomeric elements per size in different Shore hardnesses.
- ROBA[®]-ES elastomer couplings are insertable and are, therefore, also suitable for blind installation.
- The couplings are maintenance-free, media-resistant and temperature-resistant. This guarantees the highest operational safety.
- ROBA[®]-ES couplings are torsionally flexible within narrow areas. However, in comparison to the toothed belt drive, their rigidity is still 2 to 4 times higher.



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Installation Example

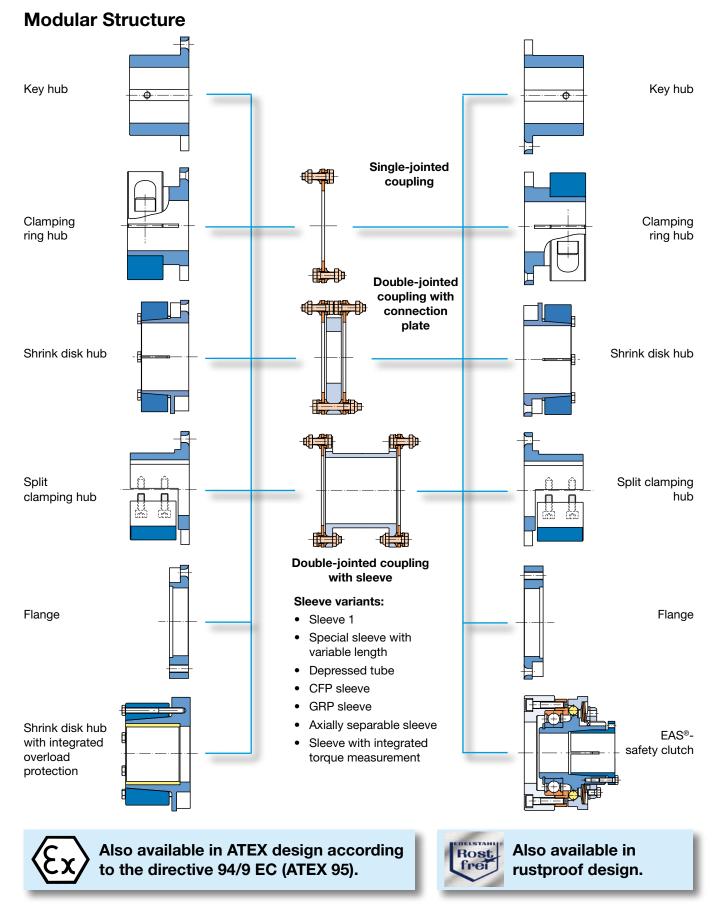


The ROBA[®]-ES shaft coupling transmits the torque backlashfree between the motor shaft and the output shaft. It also compensates for axial, radial and angular shaft misalignments.

| Tool | nical Data Di | monoiono | | | | | | | Size | | | | |
|---|-----------------|---------------------|---------------------------|---------------------------|--|-------|-------|-------|-------|------|------|------|----------------|
| Teci | nnical Data, Di | mensions | | | 14 | 19 | 24 | 28 | 38 | 42 | 48 | 55 | 65 |
| Nominal torque Elastomeric element hardness 98 Sh A | | Τ _{κΝ} | [Nm] | 13 | 17 | 60 | 160 | 325 | 450 | 525 | 685 | 1040 | |
| Peak torque Elastomeric element hardness 98 Sh A | | Τ _{κs} | [Nm] | 26 | 34 | 120 | 320 | 650 | 900 | 1050 | 1370 | 2080 | |
| Alternating torque Elastomeric element hardness 98 Sh A T _{KW} [Nm] | | | | | See coupling dimensioning in the current ROBA®-ES catalogue. | | | | | | | |) . |
| Outer diameter [mm] | | | | | 30 | 40 | 55 | 65 | 80 | 95 | 105 | 120 | 135 |
| sk | Minimum bore | | | [mm] | 6 | 10 | 15 | 19 | 20 | 28 | 35 | 40 | 45 |
| nk di | Maximum bore | | | [mm] | 14 | 20 | 28 | 38 | 45 | 50 | 60 | 70 | 75 |
| Shrink disk hub | Maximum speed | | n _{max} | [rpm] | 28000 | 21000 | 15500 | 13200 | 10500 | 9000 | 8000 | 6300 | 5600 |
| ъ | Length | | | [mm] | 50 | 66 | 78 | 90 | 114 | 126 | 140 | 160 | 185 |
| ent Sh A | | axial | ΔK_{a} | [mm] | 1,0 | 1,2 | 1,4 | 1,5 | 1,8 | 2,0 | 2,1 | 2,2 | 2,6 |
| E 8 misalignment ¹⁾ | radial | ΔK _r | [mm] | 0,09 | 0,06 | 0,1 | 0,11 | 0,12 | 0,14 | 0,16 | 0,17 | 0,18 | |
| | angular | ΔK_w | [°] | 0,9 | 0,9 | 0,9 | 0,9 | 0,9 | 0,9 | 0,9 | 0,9 | 0,9 | |
| Elast. el hardness | | static | C _{T stat.} | [10 ³ Nm/rad] | 0,12 | 0,9 | 3,7 | 4,2 | 7,4 | 13,8 | 15,1 | 20,5 | 32,8 |
| rigidity | dynamic | C _{T dyn.} | [10 ³ Nm/rad] | 0,3 | 2,2 | 7,6 | 10,1 | 19,9 | 31,1 | 44,9 | 48,2 | 67,4 | |

1) The permitted misalignments must not simultaneously reach their max. value.

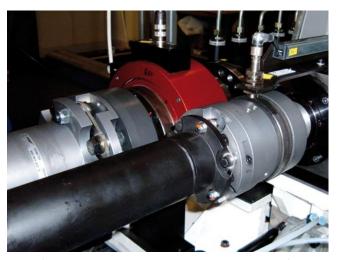




For detailed information, detailed technical data and dimensions, please see our product catalogue K.950.V_ _.GB.

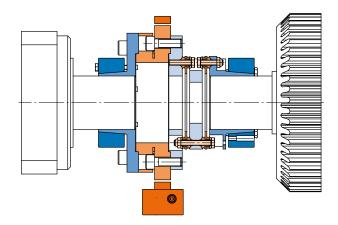
- ROBA[®]-DS couplings are not sensitive to alternating loads up to the full nominal torque.
- Due to their high performance density, they have a low mass moment of inertia.
- ROBA[®]-DS disk pack couplings transmit the torque absolutely backlash-free and with a constantly high torsional rigidity up to the nominal torque.
- On ROBA[®]-DS couplings, the full nominal torque can be used, even on alternating torques and shaft misalignments.
- They have a high misalignment capability with low restoring forces.
- ROBA[®]-DS couplings are extremely robust and can therefore be used even under difficult conditions.
- The high variant variety permits optimum coupling configuration.





ROBA[®]-DS shaft coupling combined with an EAS[®]-safety clutch in a gear test stand manufactured by the company EGM (Entwicklungsgesellschaft für Montagetechnik GmbH, Hannover).

Installation Example



By using special adaptor flanges, different measurement flanges (for torque measurement) can be integrated into ROBA®-DS couplings.

| Tool | hnical Data | Dimonoiono | | | | | | | | Si | ze | | | | | |
|------------------------|--|-----------------------|-------------------|---------------------------|-------|-------|-------|-------|--------|---------|--------|---------|-------|-------|-------|-------|
| Teci | hnical Data, | Dimensions | | | 16 | 25 | 40 | 64 | 100 | 160 | 180 | 300 | 500 | 850 | 1400 | 2200 |
| Nom | inal torque ¹⁾ | | T _{KN} | [Nm] | 190 | 290 | 450 | 720 | 1000 | 1600 | 2100 | 3500 | 5800 | 9500 | 15000 | 24000 |
| Peak | torque ²⁾ | | Τ _{κs} | [Nm] | 285 | 435 | 675 | 1080 | 1500 | 2400 | 3150 | 5250 | 8700 | 14250 | 22500 | 36000 |
| | | [mm] | 77 | 89 | 104 | 123 | 143 | 167 | 143 | 167 | 198 | 234 | 274 | 314 | | |
| | Minimum bore | ; | | [mm] | 14 | 20 | 25 | 30 | 35 | 40 | 42 | 50 | 60 | 70 | 80 | 100 |
| ¥ g | Maximum bor | e | | [mm] | 45 | 52 | 60 | 70 | 90 | 100 | 75 | 85 | 100 | 120 | 140 | 170 |
| Shrink disk hub | Maximum speed ³⁾ | | n _{max} | [rpm] | 13600 | 11800 | 10100 | 8500 | 7300 | 6200 | 7300 | 6200 | 5200 | 4400 | 3800 | 3300 |
| dis SI | Min. length single-jointed coupling | | | [mm] | 77,1 | 87,2 | 98,4 | 109,6 | 120 | 131,6 | 141,2 | 161,2 | 202 | 244 | 276 | 317,8 |
| | Min. length do | uble-jointed coupling | | [mm] | 96,2 | 106,4 | 120,8 | 137,2 | 148 | 165,2 | 172,4 | 194,4 | 242 | 295 | 334 | 383,6 |
| 4) nts | Axial displacem | 1ent ^{5) 6)} | ΔK_a | [mm] | 1,1 | 1,3 | 1,5 | 1,8 | 2,1 | 2,5 | 1,0 | 1,2 | 1,4 | 1,6 | 1,9 | 2,2 |
| | | with connection plate | ΔK _r | [mm] | 0,3 | 0,3 | 0,4 | 0,45 | 0,45 | 0,55 | 0,25 | 0,25 | 0,35 | 0,4 | 0,5 | 0,55 |
| Permitted isalignme | Radial misalignment ⁵⁾ | with sleeve 1 | ΔK_{rH} | [mm] | 1,0 | 1,2 | 1,5 | 1,8 | 2,1 | 2,2 | 1,2 | 1,25 | 1,35 | 1,7 | 2 | 2,6 |
| err sali | misalignment | with special sleeve | ΔK_{rH} | [mm] | | | | Ple | ase co | ntact t | he mar | nufactu | irer. | | | |
| <u> </u> | \Box Ξ Angular misalignment per disk pack ΔK_{w} [°] | | [°] | 1,0 | 1,0 | 1,0 | 1,0 | 1,0 | 1,0 | 0,5 | 0,5 | 0,5 | 0,5 | 0,5 | 0,5 | |
| Torsi | onal spring rigi | dity disk pack | C _{T LP} | [10 ³ Nm/rad] | 145 | 280 | 301 | 748 | 1135 | 1920 | 3000 | 3480 | 11900 | 20600 | 30150 | 46800 |

1) Valid for changing load direction and max. permitted shaft misalignments.

2) Valid for constant load direction, max. load cycles $\leq 10^{5}$.

3) Not valid for coupling with special sleeve.

6) Only permitted as a static or virtually static value.

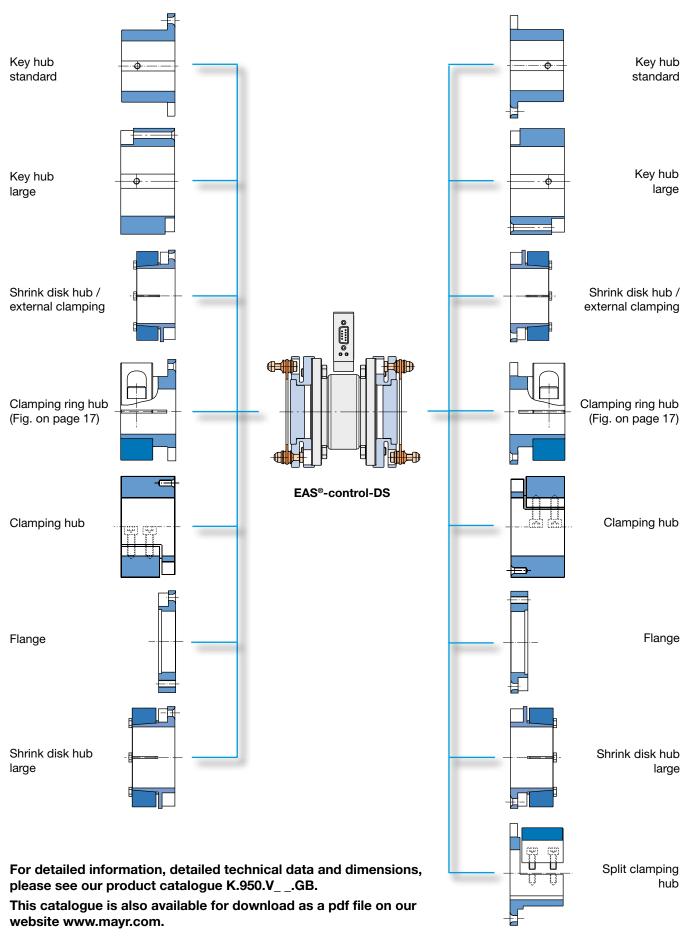
mayr®

⁴⁾ The permitted misalignments must not simultaneously reach their max. value.5) The values refer to couplings with 2 disk packs.



16

Modular Structure





Compact and Robust Torque Measurement Coupling

- Integrated into tried and tested backlash-free shaft misalignment compensation couplings
- Simple electrical and mechanical installation
- Robust and reliable
 machine element
- Completely maintenance-free

Application fields

- Process control
- Quality management
- Machine monitoring
- Test stands

Rotary signal transmitter

- Takes over energy and signal transmission
- Can be added radially
- Completely maintenance
 and wear-free

ROBA®-DS

- Compensation of shaft misalignments
- High torsional rigidity
- High permitted alternating torques
- High flexibility with reference to hub/shaft connection

Extension sensor

- Torque measurement via strain gauge
- Torque-proportional output signal

| Technical Dat | a and Main Dimensions | | | | Size | |
|--|---|--------------------|----------|-------|--------|--------|
| Technical Dat | a and Main Dimensions | | | 16 | 40 | 160 |
| Nominal torque ¹ |) 2) | T _{KN} | [Nm] | 190 | 450 | 1600 |
| Peak torque 3) | | Τ _{κs} | [Nm] | 285 | 675 | 2400 |
| | minimum hub bore | $d_{\rm Rmin}$ | [mm] | 20 | 25 | 40 |
| Clamping ring hub | maximum hub bore | d _{R max} | [mm] | 35 | 45 | 80 |
| | maximum speed | n _{max} | [rpm] | 9500 | 7000 | 4300 |
| | Length Measurement coupling | | [mm] | 178,2 | 230,8 | 329,2 |
| . | perm. axial displacement 5) 6) | ΔK_a | [mm] | 0,8 | 1,0 | 1,7 |
| Permitted misalignments ⁴⁾ | perm. angular misalignment 7) | ΔK_w | [mm] | 0,7 | 0,7 | 0,7 |
| misalignments | perm. radial misalignment ⁵⁾ | ΔK_r | [mm] | 1,1 | 1,3 | 1,8 |
| Spring | total torsional stiffness | | [Nm/rad] | 36200 | 114300 | 585000 |
| stiffnesses | angular spring stiffness 7) | | [Nm/rad] | 229 | 298 | 1990 |

Technical Data for measuring system

| - | - |
|--|---------------|
| Supply voltage | 24 VDC (±5 %) |
| Max. current consumption | 0,11 A |
| Measuring signal output (dependent on rotational direction, 5 V refers to $\rm T_{\rm KN}$ | 0 ±5 V |
| Nominal temperature range | 0 +70 °C |
| Temperature drift zero point | 0,04 % / K |
| Temperature drift measurement value | 0,03 % / K |

1) Other torques and construction sizes available on request.

2) Valid for changing load direction as well as max. permitted shaft misalignment.

3) Valid for constant load direction, max. load cycles $\leq 10^5$.

4) The permitted misalignments may not simultaneously reach their maximum values.

Technical Data for measuring system

| Band | 01 kHz (-3 dB) |
|---------------------------------|--------------------------|
| Max. data transmission distance | 3 mm |
| Protection | IP 20 |
| Max. dyn. load capability | 100 % of T _{KN} |
| Connection | Sub-D connector, 9-pole |
| Permitted speed | 0 - n _{max} |
| Max. total errors | 1 % of T _{кN} |

5) The values refer to couplings with 2 disk packs.

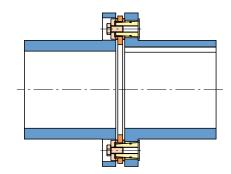
6) Only permitted as a static or virtually static value.

7) The values refer to 1 disk pack.

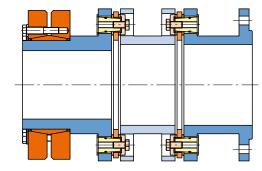
- Low screw tightening torques
- Can be installed / de-installed radially
- Easy and quick installation / de-installation
- No hydraulic installation tools required; can be installed with a torque wrench
- Backlash-free torque transmission
- FEM-optimized disk shape
- High torsional rigidity
- High performance density
- Compensation of axial, angular and radial misalignments
- Wear and maintenance-free
- High flexibility through customer-specific hubs and sleeves



Design Examples



Single-jointed coupling with key hubs



Double-jointed coupling with shrink disk hub and flange

The design of the hubs and sleeves is carried out according to the customers requirements.

| Technical De | ta Dimonoiona | | | Size | | | | | | | | |
|--|---|---------------------|------|---------------------------------|-------|--------|--------|--------|--|--|--|--|
| Technical Da | Technical Data, Dimensions | | | | 3300 | 5000 | 7300 | 11000 | | | | |
| Alternating torq | ue ¹⁾ | Τ _{κw} | [Nm] | 14700 | 22000 | 33300 | 48700 | 73300 | | | | |
| Nominal torque ²⁾ | | Τ _{κΝ} | [Nm] | 22000 | 33000 | 50000 | 73000 | 110000 | | | | |
| Peak torque ³⁾ | | Τ _{κs} | [Nm] | 44000 | 66000 | 100000 | 146000 | 220000 | | | | |
| Outer diameter | | | [mm] | 290 | 332 | 378 | 431 | 492 | | | | |
| Maximum speed [rpm] | | | 3600 | 3100 | 2700 | 2400 | 2100 | | | | | |
| | perm. axial displacement 5) | ΔK_a | [mm] | 1,6 | 1,7 | 2,1 | 2,3 | 2,3 | | | | |
| Permitted ⁴⁾ misalignments | perm. radial misalignment with special sleeve | $\Delta K_{\rm rH}$ | [mm] | please contact the manufacturer | | | | | | | | |
| | perm. angular misalignment per disk pack | ΔK_{w} | [°] | 0,4 | 0,4 | 0,4 | 0,4 | 0,4 | | | | |

1) Valid for changing load direction as well as for max. permitted

shaft misalignment.2) Valid for constant load direction as well as for max. permitted shaft misalignment.

3) Valid for constant load direction, max. load cycles $\leq 10^5$.

 The permitted misalignments may not simultaneously reach their maximum values.

5) The values refer to couplings with 2 disk packs.



ROBA®-DS Wind power module

The *mayr*[®] company's decades of experience in shaft couplings and overload systems for all areas of mechanical engineering forms a strong basis for our wind power module. The wind power module has the following characteristics:

Safe overload protection

An integrated ROBA[®]-slip bushing produced from a speciallydeveloped bushing material ensures reliable overload protection against short-circuit torques due to its minimal torque tolerance.

• Electrical insulation

The electrical insulation through the sleeve made of glass fibre-reinforced plastic prevents damage to bearings and toothing.

• Compensation of shaft misalignments

Specially-developed rustproof steel disks allow compensation of extremely high axial, radial and angular shaft misalignments. This means that only low restoring forces are generated.

Integrated brake disk

A brake disk can be integrated into the wind power module according to customer-specific requirements.

Ease of installation

The disk packs and the intermediate sleeve can be mounted and de-installed radially without axial displacement of the hub being required.

It is possible to install the disk packs with low tightening torques by using special clamping nuts.



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